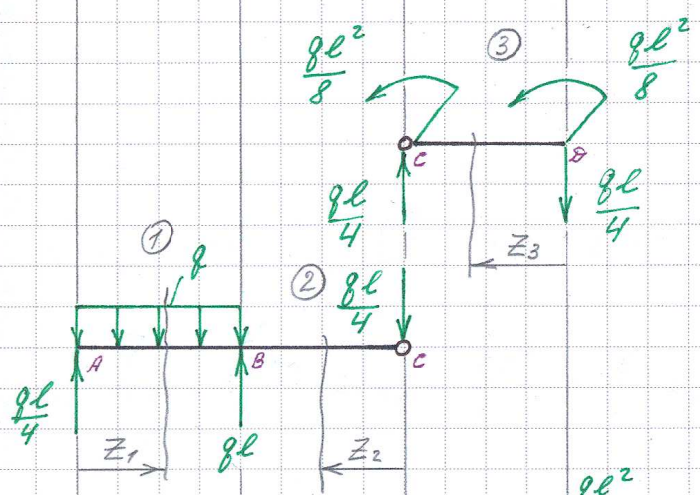
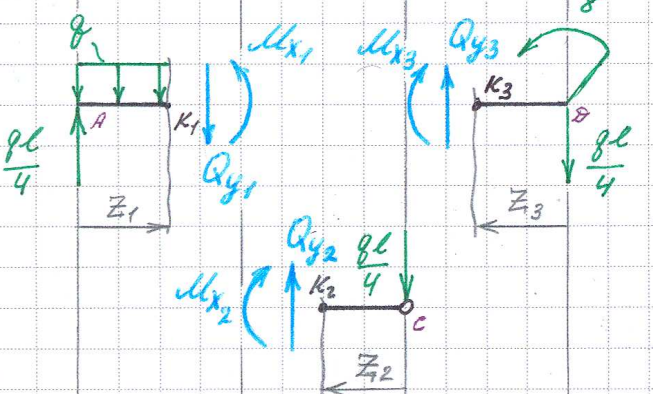


Реакции в опорах (Y_A, Y_D, M_{RD}, Z_D) и усилия в шарнире (Y_c, Z_c), находим, решая совместно систему шести уравнений равновесия (3 уравнения для части I и 3 уравнения для части II):

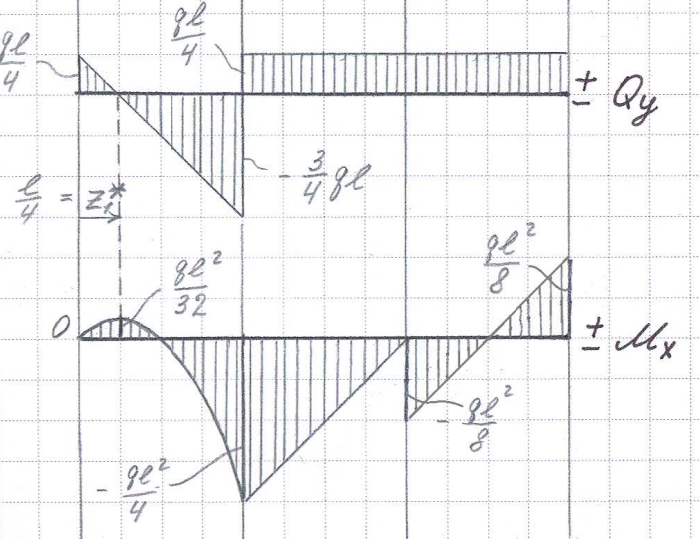


$$\begin{cases} \Sigma F_z = 0 = Z_c & (1) \\ \text{I} \left\{ \begin{aligned} \Sigma M_c = 0 &= ql \cdot \frac{3}{2}l - Y_A \cdot 2l - ql \cdot l & (2) \\ \Sigma M_A = 0 &= -ql \cdot \frac{l}{2} + ql \cdot l - Y_c \cdot 2l & (3) \end{aligned} \right. \\ \Sigma F_z = 0 = Z_D - Z_c & (4) \\ \text{II} \left\{ \begin{aligned} \Sigma M_c = 0 &= \frac{ql^2}{8} - M_{RD} + Y_D \cdot l & (5) \\ \Sigma M_D = 0 &= -M_{RD} + \frac{ql^2}{8} - Y_c \cdot l & (6) \end{aligned} \right. \end{cases}$$



Откуда:

$$\begin{aligned} Z_D = Z_c &= 0 \\ Y_A = Y_c &= \frac{ql}{4} \\ Y_D &= -\frac{ql}{4} \\ M_{RD} &= -\frac{ql^2}{8} \end{aligned}$$



Результат:

$$\begin{aligned} \Sigma F_{y1} = 0 &= \frac{ql}{4} - qz_1 - Q_{y1} \Rightarrow Q_{y1} = q\left(\frac{l}{4} - z_1\right) \\ z_1 = 0: Q_{y1} &= \frac{ql}{4} \\ z_1 = l: Q_{y1} &= -\frac{3}{4}ql \\ \Sigma M_{x1} = 0 &= \frac{ql}{4}z_1 + \frac{qz_1^2}{2} + M_{x1} \Rightarrow M_{x1} = \frac{q}{4}(lz_1 - 2z_1^2) \\ z_1 = 0: M_{x1} &= 0 \\ z_1 = l: M_{x1} &= -\frac{ql^2}{4} \end{aligned}$$

Экстремуми парадарми:

$$Q_{y_1}(z_1^*) = 0 = q \left(\frac{l}{4} - z_1^* \right) \Rightarrow \boxed{z_1^* = \frac{l}{4}}$$

$$M_{x_1}(z_1^*) = M_{x_1} \left(\frac{l}{4} \right) = \frac{q}{4} \left(l \cdot \frac{l}{4} - 2 \frac{l^2}{16} \right) = \boxed{\frac{ql^2}{32}}$$

$$\sum F_{y_2} = 0 = Q_{y_2} - \frac{ql}{4} \Rightarrow Q_{y_2} = \frac{ql}{4}$$

$$\sum M_{x_2} = 0 = -M_{x_2} - \frac{ql}{4} z_2 \Rightarrow M_{x_2} = -\frac{ql}{4} \cdot z_2$$

$$z_2 = 0: M_{x_2} = 0$$

$$z_2 = l: M_{x_2} = -\frac{ql^2}{4}$$

$$\sum F_{y_3} = 0 = Q_{y_3} - \frac{ql}{4} \Rightarrow Q_{y_3} = \frac{ql}{4}$$

$$\sum M_{x_3} = 0 = -M_{x_3} + \frac{ql^2}{8} - \frac{ql}{4} \cdot z_3 \Rightarrow M_{x_3} = \frac{ql}{8} (l - 2 \cdot z_3)$$

$$z_3 = 0: M_{x_3} = \frac{ql^2}{8}$$

$$z_3 = l: M_{x_3} = -\frac{ql^2}{8}$$